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Introduces the basic concepts of robot manipulation--the fundamental kinematic and dynamic analysis of manipulator arms, and the key techniques for trajectory control and compliant motion control. Material is supported with abundant examples adapted from successful industrial practice or advanced research topics.

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Robot Dynamics and Control - Graduate Degree in Control

10. Robot Motion Control 3 Hours 10.1 The Control Problem 10.2 Actuator Dynamics 10.3 PD Compensation 10.4 PID Compensation 10.5 Inverse Dynamics Compensation 10.6 Exercises 11. Interaction Control 2 Hours 11.1 Single Degree of Freedom Stiffness Control 11.2 Inverse Dynamics in Task Space 11.3 Impedance control 11.4 Exercises 12. Project ...

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